

Symbolic Program Decomposition & Compositional Symbolic Execution

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Introduction

The whole is greater than the sum of its parts.
– Aristotle, *Metaphysics*

Example

- A quadratic equation is given as $ax^2 + bx + c = 0$
- There is a solution iff $\Delta = b^2 - 4ac \geq 0$

```
def main(a, b, c):  
    if b*b - a*c*4 >= 0:  
        print("OK")  
    else:  
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```

```
main(1, 2, 0)  # OK
```

```
main(1, 2, 3)  # No solution!
```

- Symbex can easily find inputs for both cases

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Example

- With interval arithmetic

```
class Ival:
    def __mul__(self, other):
        if isinstance(other, int):
            other = Ival(other, other)
        vals = [self.lo*other.lo, self.lo*other.hi,
                self.hi*other.lo, self.hi*other.hi]
        return Ival(min(vals), max(vals))
```

```
def main(a, b, c):
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```

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main(Ival(1,2), Ival(2,3), Ival(-1,0)) #OK
```

- Now we have thousands of paths!

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1. Path family condition
2. Find defs
3. Split path family
4. Replace values
5. Repeat

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$$b_0 * b_0 - 4 * a_0 * c_0 \geq 0$$

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$$b_9 * b_9$$

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$\min(vals)_6, \max(vals)_6$

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$s_1.lo * o_1.lo < \dots < s_1.hi * o_1.hi : s_1.lo * o_1.lo, s_1.hi * o_1.hi$

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$b_8.lo * b_8.lo < \dots < b_8.hi * b_8.hi : b_8.lo * b_8.lo, b_8.hi * b_8.hi$

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same procedure for

$$a_9 * c_9 * 4$$

Symbolic Program Decomposition

- Using SPD, we can analyze subexpressions individually.
- The number of paths explored is $\#P_1 + \#P_2$ instead of $\#P_1 \cdot \#P_2$
- Pros of SPD:
 - exponential speed-up
 - demand-driven
- Cons of SPD:
 - relies on static dependency analysis (read: difficulties with pointers)

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Compositional Symbolic Execution

- Idea: explore each function individually
 - on first execution, generate a *summary*
 - on subsequent calls, apply this summary
- Similar speed-up as SPD: $\#P_1 \cdot \#P_2 \rightarrow \#P_1 + \#P_2 + c$

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1. Execute to function call
2. Explore all paths in function
3. Later, apply summary

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Start with random input: $b = (1, 2)$

Yields $s_1.lo * o_1.lo < \dots \wedge res.lo = s_1.lo * o_1.lo$

Example

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Flip constraints s. t. min takes 2nd element (e. g. $b = (-1, 2)$):

Yields $s_1.lo * o_1.hi < \dots \wedge res.lo = s_1.lo * o_1.hi$

Example

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Flip constraints s. t. min takes 3rd element:
Unsatisfiable (because self == other)

Example

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Flip constraints s. t. min takes 4th element (e. g. $b = (2, 1)$):

Yields $s_1.hi * o_1.hi < \dots \wedge res.lo = s_1.hi * o_1.hi$

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Continue until all combinations of `min` and `max` results are found.

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Resulting summary:

$$s_1.lo * o_1.lo < \dots \quad \wedge \quad res.lo = s_1.lo * o_1.lo \quad \vee$$

$$s_1.lo * o_1.li < \dots \quad \wedge \quad res.lo = s_1.lo * o_1.hi \quad \vee$$

...

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Caveat: Summary is not complete because now arguments can differ.

Looks Like Magic

- SMART finds the same bugs as DART...
- but uses exponentially fewer program runs
- How can this be?

Trade-Off for Compositional Methods

- Compositional methods create a trade-off

```

1  if a < b:
2      res = a
3  else :
4      res = b
  
```

 \rightsquigarrow
 $a < b \wedge res = a \quad \vee$
 $a \geq b \wedge res = b$

- 2 paths
- simple expression for res
- path condition for 1 path (same for all variables)

- 1 path
- disjunction
- path condition for many paths simultaneously (slicing)

Trade-Off for Compositional Methods

When should we trade many simple paths vs few complicated path families?

- SMART uses *functions*
 - Paths are merged if branches are in the same function
 - Some flexibility
 - Might miss opportunities for merging paths
- SPD uses *output*
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Summary

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 - More work is done by the SMT solver, less by SymbEx
 - Benefit from slicing
- SMART and SPD decide differently when to merge paths
- Same guarantees as traditional SymbEx (sound)
- Both methods offer different opportunities for abstraction

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